

Observables on Intuitionistic Fuzzy Sets: An Elementary Approach

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Abstract: *In preceding paper [6] we have presented an elementary approach to the notion of the probability on intuitionistic fuzzy events (IF-events). In the present paper we present a similar approach to the notion of an observable what is an analogue of the notion of random variable in the classical Kolmogorov theory.*

Keywords: *Probability, Intuitionistic fuzzy events, random variable.*

1. Introduction

An IF-set is a mapping $A = (\mu_A, \nu_A) : \Omega \rightarrow [0, 1]$ such that $\mu_A + \nu_A \leq 1$. The function μ_A is called the membership function, ν_A the non - membership function. If $\nu_A = 1 - \mu_A$, we obtain simply a fuzzy set $\mu_A : \Omega \rightarrow [0, 1]$.

Let us recall basic definitions of the Kolmogorov probability theory. The basic notion of the probability theory is the notion of a σ -algebra \mathcal{S} , i.e. a family of subsets of Ω satisfying the following properties:

- (i) $\Omega \in \mathcal{S}$,
- (ii) $A \in \mathcal{S} \Rightarrow \Omega - A \in \mathcal{S}$,

(iii) $A_n \in \mathcal{S} (n = 1, 2, 3, \dots) \Rightarrow \bigcup_{n=1}^{\infty} A_n \in \mathcal{S}$.

The set belonging to \mathcal{S} are called events.

Example 1.1. Consider $\mathcal{S} = \{\emptyset, \Omega\}$. Evidently \mathcal{S} is a σ -algebra. It presents an extreme situation, the smallest possible σ -algebra of subsets of Ω : the only measurable sets are the empty set \emptyset and the whole space Ω .

Example 1.2. Let \mathcal{S} consists of all subsets of Ω ($\mathcal{S} = \mathcal{P}(\Omega)$). It presents the second extreme situation: every subsets of Ω is measurable.

Example 1.3. Let $\Omega = R$, \mathcal{J} be the family of all closed bounded intervals $[a, b]$. They do not form a σ -algebra, but the convenient σ -algebra is the σ -algebra $\mathcal{B}(R)$, the smallest σ -algebra containing \mathcal{J} . The sets belonging to $\mathcal{B}(R)$ are called Borel sets.

Recall a possible (equivalent) definition of a probability P defined on a σ -algebra \mathcal{S} :

- (i) $P(\Omega) = 1$,
- (ii) $P(A \cup B) + P(A \cap B) = P(A) + P(B)$ for any $A, B \in \mathcal{S}$,

- (iii) $A_n \searrow \emptyset$ (i.e. $A_n \supset A_{n+1} (n = 1, 2, \dots), \bigcap_{n=1}^{\infty} A_n = \emptyset$) $\Rightarrow P(A_n) \searrow 0$.

A similar notion is the notion of a random variable $\eta : \Omega \rightarrow R$ what is a measurable function, i.e.

$$\xi^{-1}(I) \in \mathcal{S}$$

for any interval $I \subset R$. This mapping is theoretically described by the distribution function $F : R \rightarrow [0, 1]$ defined by the equality

$$F(t) = P(\xi^{-1}((-\infty, t))).$$

In IF-probability theory we shall work with IF-events. An IF-set $A = (\mu_A, \nu_A)$ is called an IF-event, if $\mu_A, \nu_A : \Omega \rightarrow [0, 1]$ are \mathcal{S} -measurable, i.e.

$$\mu_A^{-1}(I) \in \mathcal{S}, \nu_A^{-1}(I) \in \mathcal{S}$$

for any interval $I \subset R$.

If $A = (\mu_A, \nu_A), B = (\mu_B, \nu_B)$ are events, then we define

$$A \oplus B = (\mu_A \oplus \mu_B, \mu_A \odot \mu_B),$$

$$A \odot B = (\mu_A \odot \mu_B, \mu_A \oplus \mu_B),$$

$$\neg A = (1 - \mu_A, 1 - \nu_A),$$

where $a \oplus b = \min(a + b, 1), a \odot b = \max(a + b - 1, 0)$.

Further

$$A \leq B \Leftrightarrow \mu_A \leq \mu_B, \nu_A \geq \nu_B.$$

It is easy to see, that

$$A_n \nearrow A \Leftrightarrow \mu_{A_n} \nearrow \mu_A, \nu_{A_n} \searrow \nu_A.$$

Recall that the operations \oplus, \odot, \neg play an important role in the multivalued logic. Namely, $f \oplus g$ corresponds to the disjunction, $f \odot g$ to the conjunction and $\neg f$ to the negation. Also in the set theory they have a similar meaning: if $f = \chi_A, g = \chi_B$, then

$$\chi_A \oplus \chi_B = \chi_{A \cup B}, \chi_A \odot \chi_B = \chi_{A \cap B}, \neg \chi_A = \chi_{A'}.$$

2. IF-observables

Instead of probability or random variable respectively we shall define in our IF theory a notion of a state corresponding to probability and a notion of an observable corresponding to notion of a random variable. Denote by \mathcal{F} the family of all IF-events. The paper contains an elementary approach to the theory of IF-observables. If somebody wants to use the theory, he need not know profound mathematical backgrounds, since they are translated to a simpler language.

Definition 2.1. An IF state is a mapping $m : \mathcal{F} \rightarrow [0, 1]$ satisfying the following conditions:

- (i) $m((1, 0)) = 1, m((0, 1)) = 0$,
- (ii) $m(A \oplus B) + m(A \odot B) = m(A) + m(B)$, whenever $A, B \in \mathcal{F}$,
- (iii) $A_n \nearrow A \Rightarrow m(A_n) \nearrow m(A)$, where $A_n \in \mathcal{F}$,
- (iv) $A_n \in \mathcal{F} (n = 1, 2, \dots), A_n \searrow (0, 1) \Rightarrow m(A_n) \searrow 0$.

Definition 2.2. Let \mathcal{C} be the family of all intervals of the form $(-\infty, t), t \in R$. An IF-observable is a mapping $x : \mathcal{C} \rightarrow \mathcal{F}$ satisfying the following conditions:

- (i) $A \subset B \Rightarrow x(A) \leq x(B)$,
- (ii) $A_n \nearrow R \Rightarrow x(A_n) \nearrow (1_\Omega, 0_\Omega)$,
- (iii) $A_n \nearrow A \Rightarrow x(A_n) \nearrow x(A)$,
- (iv) $A_n \searrow \emptyset \Rightarrow x(A_n) \searrow (0_\Omega, 1_\Omega)$

Theorem 2.3. Let $x : \mathcal{C} \rightarrow \mathcal{F}$ be an IF-observable, $m : \mathcal{F} \rightarrow [0, 1]$ be an IF-state. Then the function $F : R \rightarrow [0, 1]$ defined by

$$F(t) = m(x((-\infty, t)))$$

is a distribution function.

Proof: By (iii) of Definition 2.1 and (i) of Definition 2.2 we obtain that F is non decreasing. The properties (ii),(iii) of Definition 2.1 and (ii) of Definition 2.2 imply $\lim_{n \rightarrow \infty} F(n) = 1$, the properties (iv) imply $\lim_{n \rightarrow -\infty} F(n) = 0$. Finally (iii) of Definitions 2.1 and 2.2 imply also that F is left continuous in every point $t \in R$ ■.

3. Joint IF-observable

Definition 3.1. Let $\mathcal{D} = \{(-\infty, u) \times (-\infty, v); u, v \in R\}$, $x, y : \mathcal{C} \rightarrow \mathcal{F}$ be IF-observables. The joint IF-observable of x, y is a mapping $h : \mathcal{D} \rightarrow \mathcal{F}$ satisfying

- (i) $A \subset B \Rightarrow h(A) \leq h(B)$,
- (ii) $A_n \nearrow R^2 \Rightarrow h(A_n) \nearrow (1_\Omega, 0_\Omega)$,

$$\begin{aligned}
& \text{(iii) } A_n \nearrow A \Rightarrow h(A_n) \nearrow h(A), \\
& \text{(iv) } A_n \searrow \emptyset \Rightarrow h(A_n) \searrow (0_\Omega, 1_\Omega) \\
& \text{(v) } u_n \nearrow \infty, v_n \nearrow \infty \Rightarrow \\
& h((-\infty, u) \times (-\infty, v_n)) \nearrow x((-\infty, u)), h((-\infty, u_n) \times (-\infty, v)) \nearrow y((-\infty, v)).
\end{aligned}$$

Theorem 3.2. Define $F : R^2 \rightarrow [0, 1]$ $F(u, v) = m(h((-\infty, u) \times (-\infty, v)))$. Then $F : R^2 \rightarrow [0, 1]$ is a distribution function $F(u, \infty) = F_1(u)$, $F(-\infty, v) = F_2(v)$, where F_1 is the distribution function of x , F_2 is distribution function of y .

P r o o f: It was proved in [4] and [8] that to any observables $x, y : \mathcal{C} \rightarrow \mathcal{F}$ there exists mappings

$$\widehat{x}, \widehat{y} : \mathcal{B}(R) \rightarrow \mathcal{F}$$

such that

$$\widehat{x}|_{\mathcal{C}} = x, \widehat{y}|_{\mathcal{C}} = y$$

and \widehat{x}, \widehat{y} have all properties of observables. Also it was proved that there is $\widehat{h} : \mathcal{B}(R^2) \rightarrow \mathcal{F}$ having all the properties of observables and such that

$$\widehat{h}(C \times D) = \widehat{x}(C) \cdot \widehat{y}(D)$$

(here the product $A.B$ is defined by the equality $A.B = (\mu_A \cdot \mu_B, 1 - (1 - \nu_A)(1 - \nu_B))$). Put

$$h = \widehat{h}|_{\mathcal{D}}.$$

Then

$$h((-\infty, u) \times (-\infty, v)) = x((-\infty, u)) \cdot y((-\infty, v))$$

hence

$$F(u, v) = m(x((-\infty, u)) \cdot y((-\infty, v))), u, v \in R.$$

Therefore

$$\begin{aligned}
\lim_{v \rightarrow \infty} F(u, v) &= \lim_{n \rightarrow \infty} m(x((-\infty, u)) \cdot y((-\infty, n))) = \\
&= m\left(\bigvee_{n=1}^{\infty} x((-\infty, u)) \cdot y((-\infty, n))\right) = \\
&= m\left(x((-\infty, u)) \cdot \bigvee_{n=1}^{\infty} y((-\infty, n))\right) = \\
&= m\left(x((-\infty, u)) \cdot (1_\Omega, 0_\Omega)\right) = \\
&= m(x((-\infty, u))) = F_1(u).
\end{aligned}$$

■

4. Conclusion

There is very well organized probability theory on IF-events (with respect to the Łukasiewicz operations) or more generally in MV-algebras. Of course, in the theory some notions and proofs are quite complicated. Therefore, we have presented in

the paper some simple formulations describing some important results without mentioned difficulties.

Acknowledgement. The paper was supported by Grant VEGA 1/0539/08 and Grant APVV LPP-0046-06.

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